[0001] Having thus described the invention, what is claimed is:

1	1. A hydraulic steering device for vehicles with an articulated joint between
2	major ground-engaging components of the vehicles, comprising:
3	a least one hydraulic swivelling motor for producing the steering move-
4	ment;
5	a hydraulic pump with a variable flow rate and reversal of the direction of
6	delivery, the pump in fluid flow communication with the at least one swivelling
7	motor;
8	the at least one swivelling motor further being a swivelling vane motor in-
9	corporated into the articulation joint or arranged on the turning axle of the articu-
10	lation joint.
1	2 The steering device of claim 1, wherein:
2	the variable flow pump with reversal of its delivery direction is also a con-
3	stant displacement pump, driven by a controlled variable speed electric motor.
1	The steering device of claim 1, wherein:
2	the variable flow pump with reversal of its delivery direction is a variable
3	displacement axial piston pump with a swashplate.
1	A The steering device of claim A subspace.
1	4 The steering device of claim 1, wherein:
2	the at least one swivelling motor is arranged above and/or beneath the ar-
3	ticulation joint.
1	5. The steering device of claim 2, wherein:
2	the at least one swivelling motor is arranged above and/or beneath the ar-
3	ticulation joint.
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- 1 6. The steering device of claim 3, wherein:
- 2 the at least one swivelling motor is arranged above and/or beneath the ar-
- 3 ticulation joint.
- 1 7. The steering device of claim 1, further including:
- an electronic controller connected to and controlling the operation of the
- 3 pump.
- 1 8. The steering device of claim 7, wherein:
- 2 the electronic controller is a micro-processor.
- 1 9. The steering device of claim 2, further including:
- 2 sensors for recording the steering angle and further system parameters of
- 3 state are positioned on the at least one motor.
- 1 10. The steering device of claim 3, further including:
- 2 sensors for recording the steering angle and further system parameters of
- 3 state are positioned on the at least one motor.
- 1 11. The steering device of claim 8, further including:
- 2 sensors for recording the steering angle and further system parameters of
- 3 state are positioned on the at least one motor.
- 1 12. The steering device of claim 7, further including:
- 2 a joystick connected to said electronic control element for setting the
- 3 steering angle.

- 1 13. The steering device of claim 12, wherein the joystick includes a force-
- 2 feedback function.
- 1 14. The steering device of claim 11, further including:
- a joystick connected to said electronic controller for setting the steering
- 3 angle.
- 1 15. The steering device of claim 14, wherein the joystick includes a force-
- 2 feedback function.
- 1 16. The steering device of claim 11, wherein:
- the at least one swivelling motor is a swivelling vane motor.
- 1 17. The steering device of claim 16, further including:
- a set angle prescribed by the operator is recorded in the micro-processor,
- 3 and depending upon that the quantity and direction of the volume flow to the at
- 4 least one hydraulic steering motor is influenced.
- 1 18. The steering device of claim 17, wherein:
- 2 the actual angle of the steering device is recorded in the micro-processor
- 3 and the volume flow to the steering motor is controlled by a control algorithm
- 4 which is selectively variable depending upon the operating state of the vehicle, in
- 5 particular a steering angle control and/or a steering angle velocity controller.